

A bulk superconducting MgB₂ cylinder for holding transversely polarized targets

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Abstract

An innovative solution is being pursued for the challenging magnetic problem of producing an internal transverse field around a polarized target, while shielding out an external longitudinal field from a detector. A hollow bulk superconductor can trap a transverse field that is present when cooled through its transition temperature, and also shield its interior from any subsequent field changes. A feasibility study with a prototype bulk MgB₂ superconducting cylinder is described. Promising measurements taken of the interior field retention and exterior field exclusion, together with the corresponding long-term stability performance, are reported. In the context of an electron scattering experiment, such a solution minimizes beam deflection and the energy loss of reaction products, while also eliminating the heat load to the target cryostat from current leads that would be used with conventional electromagnets.

Keywords: Bulk superconductor, MgB₂, HDice, superconducting shield, trapped field, zero-field cooling

1. Introduction

The determination of the spin-dependent amplitudes in a reaction between non-zero spin particles always requires measurements with different orientations of the target polarization. In the case of spectrometers that are not accompanied by large magnetic fields at the target, such as those incorporating torodial magnets, elaborate changes to a cryostat are usually required to provide holding fields for different target spin orientations. For spectrometers with strong magnetic fields in the target region, changing the natural target spin alignment becomes a formidable problem. The latter arises in the study of transverse spin effects with an 11 GeV electron beam in Hall-B of Jefferson Laboratory, where a transversely polarized hydrogen target must be placed within the longitudinal field of the central solenoid of the CLAS12 detector system [1, 2, 3]. We describe here a novel solution to such problems.

A hollow bulk superconductor is able to provide a transverse holding field inside, while adjusting its internal currents to shield any outside field [4, 5]. The latter feature is an important improvement with respect to a conventional coil-based magnetic solution. Additional advantages include minimal space needed to fit within the target cryostat, maximal field compactness to reduce electron beam deflection in the transverse field, the absence of cryogenic load from current leads and the ability to operate without a copper stabilizer, which reduces the energy-loss of particles traversing the material. The particular choice of MgB₂ for the superconducting material results in a small mass and Z in the path of reaction products, which fur-

ther minimizes their energy-loss. Polarized hydrogen targets inherently require low temperatures, and as a result, the cooling of an MgB₂ cylinder to 4K can be readily incorporated within the target cryostat. Finally, for the planned set of transverse experiments with polarized HD in the CLAS12 detector, the necessary eld manipulation is straightforward to accommodate within the installation procedure of the HDice frozen-spin polarized target [6, 7].

The choice of magnesium diboride as the superconductor is motivated by its high critical current, critical field and transition temperature (39 K), by its availability in suitable shapes, as well as by its low density and low average- Z [8, 9]. Over the relevant temperature and field regime, it operates as a hard type-II superconductor, despite the presence of two coherence lengths.

The details of an apparatus to test the transverse magnetic behavior [7, 10] of MgB₂ cylinders are given in Section 2. The measurements are presented in Section 3, while conclusions are summarized in Section 4.

2. A test bed for an MgB₂ prototype cylinder

The design of the system has been described earlier [7], but additional details of the as-constructed setup are given here. Figs. 1 and 2 provides an overview.

2.1. Mechanical refrigerator

The superconducting cylinder is cooled by a cold head (Edwards 6/30). The lowest temperature that has been reached is 11.1 ± 0.1 K. The sample temperature is controlled by resistive heating of the cold head. The cold

59 head, a thermocouple and a heater are all in a low field
60 zone [7].

61 2.2. External magnet

62 The magnetic field was provided by a VARIAN electro-
63 magnet (model V3603) with a maximum current of 180 A.
64 The magnet power supply (Agilent 6692A) was remotely
65 controlled via GPIB. The maximum field generated at the
66 center was about 980 mT, as measured by a Hall sensor
67 (Arepec HHP-NU). The Hall probe had an active area of
68 1.25 mm x 0.5 mm and was designed to operate with fields
69 up to 5 T in the temperature range from 1.5 K to 350 K,
70 with an additional correction [11] required at lower tem-
71 peratures.

72 2.3. Vacuum system and thermal insulation

73 The vacuum system consist of two cylindrical chambers,
74 a stainless steel top one, with all the vacuum penetrations,
75 and an aluminum bottom one. The cold head is mounted
76 on a CF100DN flange on the top of the upper chamber.
77 A CF63DN flange holds a turbo pump (Agilent Turbo-V
78 81-M) backed by a scroll pump (Varian SH110). Pres-
79 sures are monitored by a Penning gauge (Pfeiffer PKR
80 251) placed at the front of the turbo and a Pirani gauge
81 (Pfeiffer PRT81) at the exit. A CF40DN flange holds two
82 sub-miniature D9 feedthroughs carrying three sets of 4-
83 wire leads for the Hall probe and two sample temperature
84 sensors, as well as two sets of 2-wire leads for the cold head
85 thermocouple and the heater, to control the cold head tem-
86 perature.

87 The MgB_2 cylinder was fitted into the bore of a 380 mm¹¹⁴
88 long, 50 mm diameter sample can - a copper rod, thermally¹¹⁵
89 connected to the second stage of the cold head (with 10 K
90 nominal temperature). Surrounding this was a 3 mm thick
91 copper thermal shield connected to the cold head's first¹¹⁶
92 stage (77 K nominal temperature). Thin indium foils were¹¹⁷
93 used in all thermal joints. The aluminum chamber had an¹¹⁸
94 outer diameter of 70 mm and a wall thickness of 3 mm.¹¹⁹
95 Three layers of Myoflex sheet insulation (C7-110) [12] were¹²⁰
96 wound around the 62 mm diameter thermal shield along¹²¹
97 the whole length of the aluminum vacuum chamber. Two¹²²
98 bands of Myoflex foil, about 2 cm wide, were used as spacers¹²³
99 at the bottom and the top of the sample can.

100 During the initial set of measurements (Figs. 3, 4, and¹²⁴
101 5), shaped epoxy spacers were used at the bottom of the
102 thermal shield to define its position. In a subsequent im-¹²⁵
103 provement, the epoxy spacers were replaced with small (~ 1
104 cm^2) five-layer assemblies of myoflex, positioned at 120° ¹²⁶
105 intervals around the cylinder. This improved the insula-¹²⁷
106 tion between the cooling arm and its shield and lowered¹²⁸
107 the base temperature (Figs. 6, 7 and 8).¹²⁹

108 The pressure during test periods was below 10^{-8} mbar¹³⁰
109 within the sample can and thermal shield. Nonetheless,¹³¹
110 the minimum temperature of the sample increased slowly¹³²
111 over time. Since the base temperature could be recovered¹³³
112 by warming up the system and pumping on the insulating¹³⁴

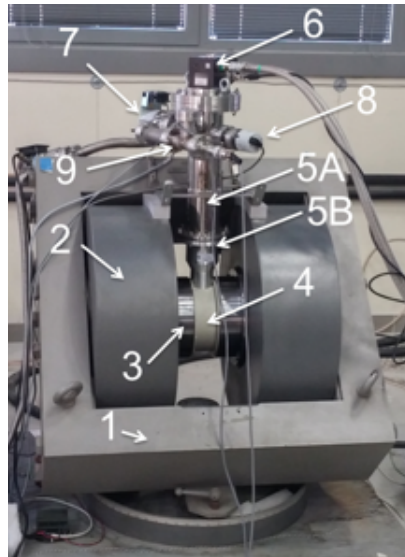


Figure 1: An overview of the equipment [7] shows the iron yoke (1), the coils (2) and the iron poles (3). The aluminum chamber is inserted into a nylon support (4), which is fixed to the poles (3). The stainless steel (5A) and aluminum (5B) vacuum chambers are fixed to the coils (2) and the yoke (1). A cold head (6) is placed on top of the vacuum chamber (5); the turbomolecular pump (7) is connected to one side. Two additional flanges carry a pressure sensor (8), and electrical feedthroughs (9).

vacuum, we attributed the slow temperature rise (eg. top panel of Fig. 5) to a buildup of frozen gas, which deteriorated the thermal isolation.

2.4. Temperature measurement

Two temperature sensors are placed on the bottom of the sample can, a Rhodium Iron (RhFe) calibrated sensor from Oxford Instruments, and a cryogenic linear temperature sensor (CLTS) from VISHAY. The CLTS is preferred above 30 K and the RhFe below. Accuracy of the measured temperature without magnetic field is about 10 mK, but increases to 50 mK with fields up to 1 T. Both sensors have high reproducibility: 5 mK at 4.2 K for the RhFe.

2.5. Data acquisition

LabView routines are used to 1) adjust the Oxford ITC-503S heater controller, 2) control and record the power supply settings of the external magnet, 3) readout and record pressure values from the Pfeiffer TPG256A, 4) acquire, interpret and store temperature sensor resistances measured by a Keithley scanner (199 System DMM/Scanner), and 5) readout and store data from the Hall probe controller (USB2AD by Arepeco). The routines are synchronized to within ± 0.5 seconds.

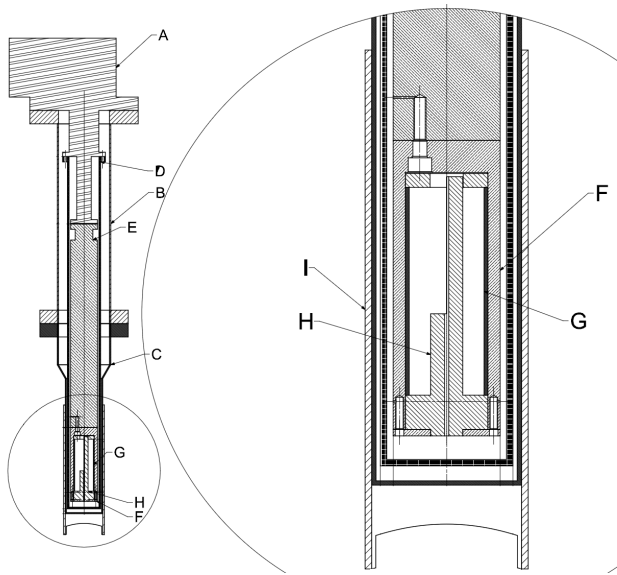


Figure 2: A schematic drawing of the cold head and the inner parts of the chamber and the cylinder holder is shown with an expanded view on the right: the cold head (A), the stainless steel vacuum chamber (B), the aluminum vacuum chamber (C), the copper thermal shield connected to first stage of the cold head (D), the Copper rod connected to second stage of the cold head (E), the Copper chamber which hosts the sample cylinder (F), the MgB_2 cylinder (G), a PFTE (C_2F_4 , Teflon) Hall probe holder (H), and a PEEK (Polyether ether ketone) support (I).

2.6. Thermal cycle

About 7.5 hours are required to cool from room temperature to near 13 K (see Fig. 3). Using the cold head heater at full power (65 W), it takes about one hour to heat the sample can to 60 K, which is done after each test to insure a complete transition before the next cool down and test. The trapped field disappears at a (CLTS) temperature of 38.8 K, close to the MgB_2 critical temperature of 39 K. One and a half hours are needed to cool back to near 13 K.

3. Experimental Results

Measurements of the trapping and shielding of the transverse field from the external dipole were performed on a prototype MgB_2 cylinder made by the Reactive Liquid Infiltration (RLI) process [13], 86 mm long with a 39 mm outer diameter. While the nominal wall thickness was 2 mm, the material thinned to 1 mm in sections near the ends. This limited the maximum internal current, so that the thinned regions effectively dominated the performance at high field.

A simulation tool is under development at JLAB [14], which calculates eddy currents in a material whose conductivity is continuously adjusted to reproduce the Bean-

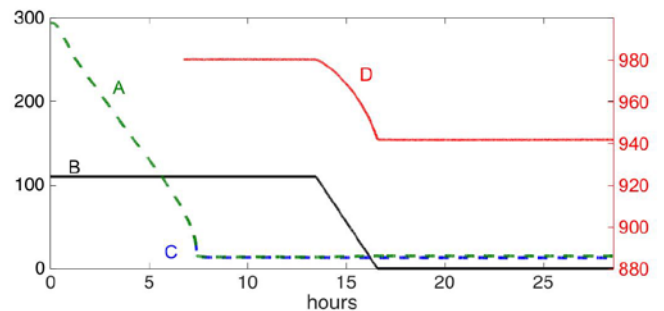


Figure 3: A field trapping cycle is shown, with the system starting at room temperature. The green-dashed (A) and blue-dashed (C) curves are the sample temperatures, in Kelvin with their scale on the left, as recorded with the CLTS and RhFe sensors, respectively. The external magnet current (B), in Amps with the left-hand scale, is shown in solid black. The field at the center of the MgB_2 cylinder (D), in mT with scale on the right, is shown as the solid-red curve.

model critical state with the measured MgB_2 critical current density [9], as a function of field and temperature. Some initial results are discussed in ref. [14] and a detailed comparison will be given elsewhere. Here we focus on the experimental performance.

3.1. Trapped field measurements

i) Cooling and trapping:

The trapped field test is performed by field cooling (FC). With an external field applied, the sample is cooled from room temperature to about 13 K. After the system stabilizes at the minimum temperature, the external field is ramped to zero while the residual field of the MgB_2 cylinder is measured. A typical cycle is shown in figure 3.

Note that there is no impact on the central field when the cylinder goes superconducting near 39 K, as expected of a hard Type-II superconductor. Furthermore, the granularity of the flux tube lattice penetrating the MgB_2 (~ 150 nm) is not visible at this distance scale. The external field at a current of 110 A, 980 mT, produces a trapped field of 942 ± 1 mT. The failure of the superconductor to fully replace the external field reflects the open ends of the cylinder, which prevent the induced super-currents from following an optimum path. As the ramp down proceeds, the critical current limitation forces the additional current to follow successively less-optimal paths, producing a faster than linear fall off.

ii) Long term stability:

Long term trapped field measurements have been performed for different externally applied fields. A stability test performed at a current of 70 A (producing 664 mT) is shown in Fig. 4. The trapped field is 644 mT, and both temperature and field show an extremely stable behavior out to 170 hours. (The oscillations of the magnetic field

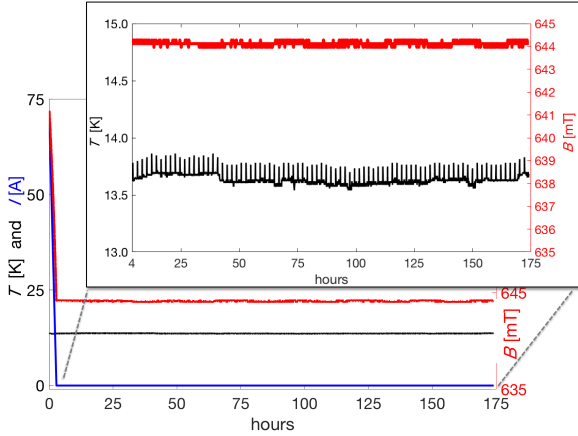


Figure 4: Typical trapped field results are plotted for an 170 hour test period. The external magnet current, in Amps with the left-hand scale, is shown as the blue curve. The solid-black curves give the temperature, in Kelvin with the left-hand scale. The field in the center of the cylinder is shown as the solid red curves, in mT with their scale on the right. The temperature and central field are shown with an expanded scale on the top.

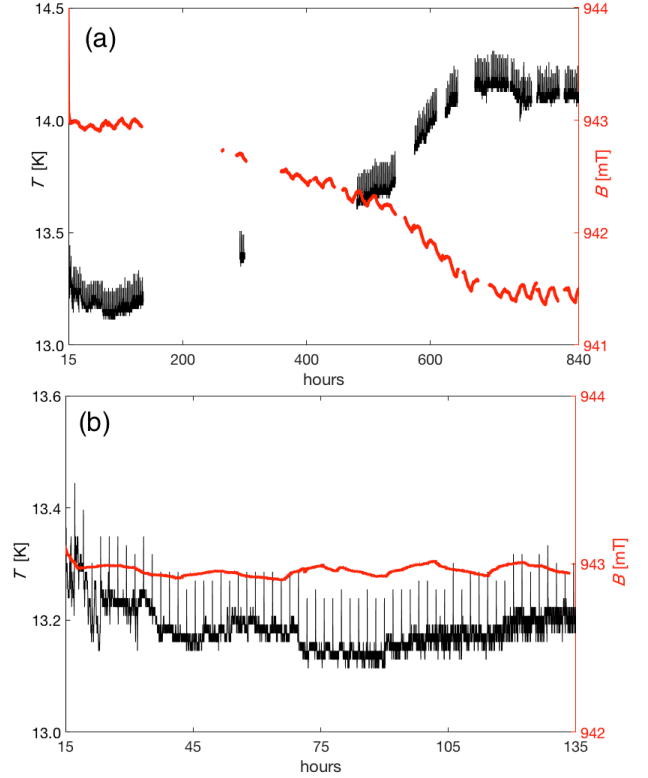


Figure 5: (a) Trapped field measurements are logged here, out to 800 hours. The MgB_2 temperature and central field are shown as black and red curves, with scales on the left and right, respectively. The external field is zeroed at 15 hours. (Gaps in the top panel result from data recording failure.) The field drift of about 1.5 mT is due to the temperature drift. (b) The bottom panel shows the first 140 hours with an expanded scale.

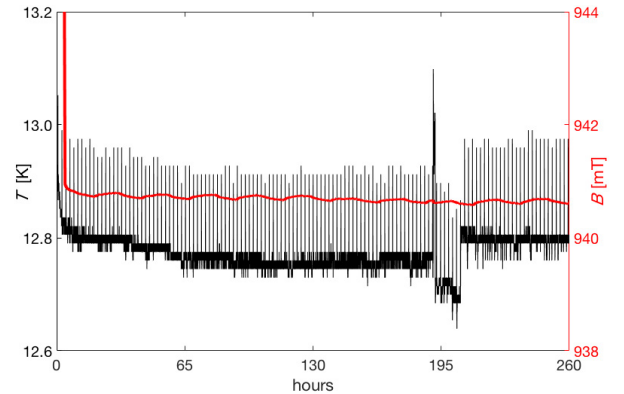


Figure 6: The MgB_2 temperature and central field are shown here, with the same representation as in figure 5. These data were collected a year and tens of thermal cycles after those of figure 5 following improvements in thermal isolation, which led to the lower base temperature.

191 are artifacts from the readout, while the shorts spikes in
 192 the temperature are produced by the cold-head cycle.)

193 Extended stability measurements at a higher field are
 194 reported in Fig. 5, where the trapped field and tempera-
 195 ture have been tracked for about one month. During the
 196 FC, the current of the power supply is 110 A (producing
 197 980 mT). After ramping down the external magnet, the
 198 internal MgB_2 field is 943 mT. We believe that the mea-
 199 sured field decay of about 1.5 mT is due to the tempera-
 200 ture increase of about 1 K over this extended period. In the
 201 lower panel of Fig. 5, the first 135 hours are expanded
 202 in order to compare the behavior with the lower field mea-
 203 surements of Fig. 4. Once again, the temperature and field
 204 are very stable. The simulated values of trapped fields at
 205 70 A and 110 A are 637 mT and 938 mT, respectively, in
 206 good agreement with these measurements [14].

207 Following improvements in the thermal isolation of the
 208 sample region (Section 2.3), another FC study has been
 209 performed a year later (and after tens of thermal cycles),
 210 using the same external field. This has yielded similarly
 211 consistent values, as shown in Fig. 6. (Here, the trapped
 212 field appears slightly lower than that of Fig. 5(b), despite
 213 the lower temperature; this reflects small variations in po-
 214 sitioning the Hall probe.) A reliably consistent level of
 215 performance in trapping fields following FC is evident.

216 3.2. Shielding field measurements

217 Transverse shielding measurements have been per-
 218 formed by powering the external magnet after zero field
 219 cooling (ZFC). A typical cycle for this measurement is
 220 shown in Fig. 7. The cylinder shields most of the field
 221 generated by the external magnet (980 mT), with only a

222 small residual magnetic field penetrating the volume inside
 223 the cylinder.

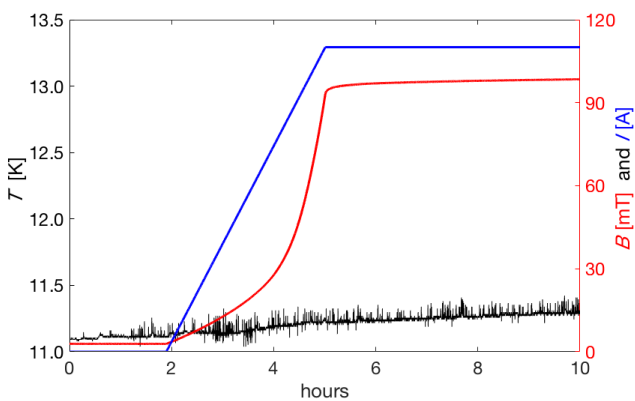
224 The maximum critical current that can be sustained in
 225 MgB_2 is a strong function of temperature [9], and as a
 226 result its effectiveness in shielding an external field is temper-
 227 ature dependent. This is confirmed in Fig. 8, where
 228 the leakage field clearly tracks the temperature measured
 229 by the RhFe sensor. The residual field at the center of
 230 the cylinder is 120 ± 5 mT when the MgB_2 temperature
 231 is in the range of 13.0 ± 0.5 K. (The simulated level of
 232 the leakage field is 71 mT at 13 K, in qualitatively good
 233 agreement with these observed results [14].)

234 While these studies were limited to 11 K, the trend in
 235 Fig. 8 projects very small residual fields within an MgB_2
 236 shell operated at 4 K.
 237

238 3.3. Moving the MgB_2 cylinder

239 The planned scheme for using an MgB_2 shell requires
 240 that it be cooled in a transverse field to trap transverse
 241 flux, after which a solid polarized target of HDice would
 242 be inserted vertically into the target cryostat. Next, the
 243 target cryostat would be rotated horizontal and wheeled
 244 into the bore of the CLAS12 solenoid. At that point the
 245 field of that solenoid would be ramped up for data taking.
 246 This process would subject the cylinder to unavoidable
 247 shocks and vibrations. Its ability to withstand this must
 248 be tested.

249 For a trial move, the vacuum chamber containing the
 250 MgB_2 cylinder was extracted from the external magnet by
 251 a crane. (The system remained connected to the vacuum
 252 pumps, and the cold head remained powered during the
 253 test.) A trapped field of 564.7 mT was maintained during
 254 removal and return with no detectable field loss.



279 Figure 7: A typical shielding cycle is shown, with the
 280 magnet energized after the system is cold. The external
 281 magnet current (in blue) in Amps, and the field at the
 282 center of the cylinder (in red) in mT, are plotted with their
 283 scales on the right. The temperature (in black) is shown
 284 versus time with its scale on the left. The temperature
 285 (RhFe) is 11.1 K at the starting point.
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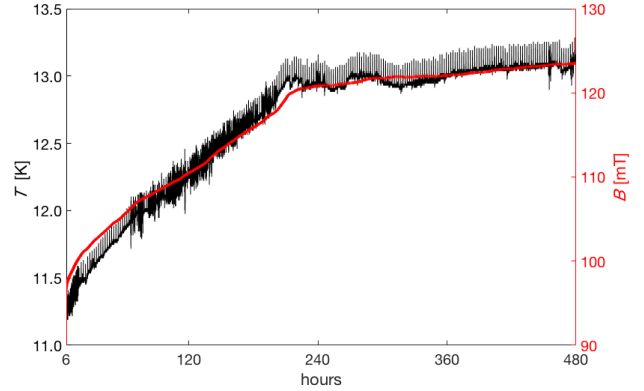


Figure 8: The temperature and magnetic field penetration
 during shielding measurements is plotted over a 20-day
 period. The temperature is 11.2 K after 6 h from the
 starting point of figure 7 and it ends at 13.2 K. The field
 penetration is visible and it tracks the temperature (RhFe
 sensor).

4. Conclusion

A novel solution for the challenging magnetic problem
 of placing a transversely polarized target in a longitudi-
 nal field has undergone an initial feasibility study in an
 apparatus assembled for that purpose.

Several tests of trapping and shielding of a transverse
 field were performed on an MgB_2 cylinder at working tem-
 peratures between 11 and 13 K. The maximum trapped
 field at the center of the cylinder was 942 mT, limited
 by an available external field of 980 mT. During shielding
 studies, the same external field was reduced by an order
 of magnitude within the cylinder, with yet smaller values
 expected at temperatures near 4K. The trapped field was
 monitored for up to 800 hours, with only minor losses
 due to temperature drift, and the cylinder did not show
 any loss of trapped field due to vibration or movement
 of the assembly.

This feasibility study has demonstrated that a MgB_2
 cylinder has the features essential for the installation of
 a transversely polarized target into the CLAS12 detector
 at Jefferson Lab.

Potentially, this use of superconducting shells to man-
 age local fields could have a variety of applications, such
 as providing the capability of easily switching spin orien-
 tations in a fixed-target cryostat, orienting spins in
 polarized gas targets internal to storage rings, or enab-
 ling the use of transverse fields in close proximity to
 the beam of a storage ring [15, 16]. An advantage of
 the particular solution described here is the use of a
 relatively simple cryo-cooler to reach temperatures that
 are sufficient to support internal currents within the
 superconductor that can maintain or cancel up to 1 T
 fields.

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