1 ABSTRACT

2 Animal species differ considerably in their ability to detour around a see-through obstacle to reach a 3 goal positioned behind it. This variation is commonly assumed to derive from interspecific differences in the cognitive functions involved in the execution of the task, such as spatial abilities 4 and inhibitory motor control. A teleost fish, the guppy (Poecilia reticulata), has been recently found 5 to outperform many mammals and birds in this type of task. To determine whether this is a typical 6 7 condition in teleost fish or whether detour abilities vary among fish species as observed in 8 mammals and birds, we compared four distantly related teleosts in the transparent barrier task using 9 a group of conspecifics as goal. The scores of three species (Poecilia reticulata, Xenotoca eiseni, 10 Oryzias sarasinorum) were similar to those previously reported for fish. The remaining species, the zebrafish (Danio rerio), showed a much higher performance, close to that of warm-blooded animals 11 with highest scores (e.g., corvids and monkeys). In comparative cognition studies, contextual 12 13 variables rather than differences in cognitive ability may be responsible for observed differences between species. In a second experiment, we found that the four species were similarly gregarious, 14 excluding a different motivation to reach the target as an explanation for the different performance. 15 In another experiment, however, we provided evidence that zebrafish's higher detour performance 16 17 might be due to a sensory advantage. Zebrafish used olfactory cues (towards which the barrier was 18 opaque) to navigate to the social stimulus, whereas the guppy, which we used as a control species, preferentially relied on visual information. This study highlights the importance of sensory 19 differences as a source of potential experimental confound in comparative cognition research. 20

21

22 Keywords: cognitive abilities, comparative cognition, detour, fish cognition, sensory differences

23 INTRODUCTION

For many animal species, survival and reproductive success may hinge on the ability to efficiently 24 find the way to resources such as food, social groups, mating partners and refuge. Animals that live 25 in complex environments frequently face situations in which they must bypass an obstacle, such as 26 a gap in the route or thick vegetation, to reach a resource located behind it (Eloff, 1951; Tarsitano & 27 Andrew, 1999; Zeil & Layne, 2002). This behaviour, often referred to as detour behaviour, requires 28 the animal to temporarily move away from the goal in order to find an indirect route to it. 29 Several cognitive functions are thought to influence the ability to accomplish the detour behaviour, 30 including spatial learning abilities, reasoning and inhibitory motor control (Kabadayi, Bobrowicz, & 31 32 Osvath, 2018). For the past century, laboratory studies have investigated these abilities using the detour task (e.g. Kabadayi et al., 2018; Köhler & Winter, 1927; Regolin, Vallortigara, & Zanforlin, 33 1994; Thorndike, 1911; Zucca, Antonelli, & Vallortigara, 2005). Typically, a barrier is placed 34 35 between the subject and the goal, a biologically relevant stimulus. The performance is generally scored in terms of latency to reach the goal or the number of successful attempts, namely reaching 36 the goal without touching the barrier (Kabadayi et al., 2018). Using variations of the detour task, in 37 terms of number of trials and type of barrier, it is possible to investigate different cognitive abilities 38 39 underlying the detour behaviour. For example, by testing subjects in a single trial it is possible to 40 assess whether they can solve the detour problem the first time they face it, which is considered an indication of capacities for insight or spatial reasoning (Tarsitano & Andrew, 1999; Köhler & 41 Winter, 1927). By testing subjects in repeated trials, it is possible to assess their learning ability, 42 43 indicated by performance improvement over trials (Gatto, Lucon-Xiccato, & Bisazza, 2018; Kabadayi, Krasheninnikova, O'neill, van de Weijer, Osvath, & von Bayern, 2017; van Horik, 44 Langley, Whiteside, Laker, Beardsworth, & Madden, 2018). 45 More recently, two variants of this paradigm, the transparent barrier detour task and the transparent 46

47 cylinder task, have been used to study inhibitory motor control (Kabadayi, Taylor, von Bayern, &

Osvath, 2016; MacLean et al., 2014; Lucon-Xiccato, Gatto, & Bisazza, 2017; van Horik et al., 48 49 2018). In both variants, animals could see a reward (e.g. food or conspecifics) behind a transparent barrier or inside a transparent cylinder, which creates a strong lure for a direct reach. Inhibiting such 50 prepotent direct response is necessary for successful detour. To accomplish this inhibition, animals 51 are expected to rely on inhibitory control, a cognitive process that allows an individual to override 52 an automatic or compelling response to adopt behaviour more appropriate to the specific 53 54 circumstance (Chudasama, 2011; Diamond, 2013; Gilbert & Burgess, 2008). Comparative research on inhibitory control with the detour task has revealed compelling performance differences across 55 species. For example, MacLean and colleagues (2014) found that some great apes, such as 56 57 chimpanzees and Bornean orangutans, achieved a mean performance of 95% of correct responses, 58 while some prosimians and Old World monkeys, such as Coquerel's sifakas and golden snub-nosed monkeys, achieved far below 50% correct responses. In this investigation, a correct response 59 60 consisted in reaching a food portion inserted in a transparent cylinder without touching the cylinder; instead a response was considered as incorrect if a subject touched the transparent cylinder before 61 reaching the food. According to this study, the best predictor of detour task performance was 62 absolute brain size of a species, suggesting that large brained animals are capable of higher levels of 63 64 inhibitory control (MacLean et al., 2014). Several studies have also suggested that other factors, 65 related to the evolutionary history and ecological adaptation of each species, may have shaped the cognitive abilities at the basis of detour task solution (Amici, Aureli, & Call, 2008). 66 The aforementioned interpretations of studies on detour behaviour rely on the assumption that 67 68 differences in performance between species are due to variability in the cognitive functions involved in the solution of the task. However, the observed interspecific differences may also be 69 70 due to non-cognitive contextual variables that affect the execution of the detour task (Macphail, 1987; Shettleworth, 2010). For example, a more attractive goal is expected to create a stronger lure 71 for a direct approach, making it harder to correctly execute the detour. Animals presented with a 72

more desirable target, such as a greater amount of reward or a closer goal, decrease their capacity to 73 74 execute the detour task (e.g., Gatto et al., 2018; Regolin et al, 1994). Even when the same goal is 75 placed behind a barrier, the value assigned to it and the consequent motivation to reach can vary among species (and individuals), thus creating a potential experimental confound. 76 77 Interspecific differences in the detour task could also emerge as a consequence of variation in sensory systems. In the comparative study by MacLean and colleagues (2014), macrosmatic 78 79 species, such as canids and rodents, showed performances higher than most microsmatic species and not dissimilar from that of great apes. This result might be related to the different way a 80 81 transparent barrier is perceived by a species that relies on olfaction rather than vision: while the 82 vision of the goal creates a strong lure through the barrier, the odour from the stimulus follows the 83 same pathway that the animal has to take to correctly solve the detour task. A tiny teleost fish, the guppy (Poecilia reticulata), demonstrated performances in detour tasks that 84 85 exceeded those of many mammals and birds (Gatto et al., 2018; Lucon-Xiccato et al., 2017; Santacà, Busatta, Savaşçı, Lucon-Xiccato, & Bisazza, 2019). However, it is not clear whether the 86 87 performance of guppies is representative of that of teleost fish. Detour performance might vary considerably among teleost species as observed among mammals and birds, and guppies might be a 88 89 species exceptionally skilled because of ecological adaptations. Indeed, ecological adaptations often 90 prompt the evolution of a remarkable cognitive capacity such as in the case of spatial memory in

91 food storing corvids (Healy & Krebs, 1992).

In the first experiment of this study, we investigated interspecific differences in detour behaviour by testing four fish species: guppies (*Poecilia reticulata*), zebrafish (*Danio rerio*), red-tailed splitfin fish (*Xenotoca eiseni*) and Sarasins minnows (*Oryzias sarasinorum*). As the obstacle, we used a transparent barrier; thus, our task was expected to measure various cognitive skills including spatial and inhibitory abilities. As a goal, we used a shoal of conspecifics because the four species usually live in group. The four species tested in this study have evolved independently for a long time, more

than 100 million years in some cases. Given that mammalian species with less than half such 98 divergence time exhibited remarkable differences in detour performance (MacLean et al., 2014), 99 100 these fish species were expected to show some variation in detour performance. Moreover, there is evidence that detour abilities might vary according to the habitat in which a species has evolved 101 (Zucca et al, 2005). Despite some similarities among the four species, such as size, lifespan, and 102 social behaviour, there are differences in their original habitats that may cause variation in detour 103 104 performance. Two species, guppies and zebrafish, occupy a variety of habitats from lowland slow moving streams to fast running mountain brooks, which are often rich of vegetation, rapids, rocks 105 and other obstacles (Magurran, 2005; Roy & Bhat, 2018). The red-tailed splitfin fish live in similar 106 107 environments, and in some cases in lakes, although usually these habitats have less vegetation (Piller, Kenway-Lynch, Camak, & Domínguez-Domínguez, 2015). Conversely, Sarasins minnows 108 are endemic of Poso lake, a large and deep basin in central Sulawesi and mainly show pelagic life 109 110 style (Kottelat, 1990; Parenti, 2008). The pelagic species has evolved in a habitat with few obstacles, which may cause relaxed selection on detour abilities compared to the remaining species. 111 In the second and third experiments of this study, we investigated possible non-cognitive causes for 112 the differences observed in Experiment 1. In particular in Experiment 2, we studied whether the 113 four species differed in their sociality and therefore whether social reward could constitute a 114 115 different lure, making the detour task more or less difficult to solve. If a different motivation is the cause of interspecific differences, highly gregarious species were expected to show the poorest 116 performance. In Experiment 3, we tried to understand whether the high detour performance of 117 118 zebrafish could be due to the use of a different sensory system. As observed in mammals, there is a large variation among fishes in the development of the different sensory systems (Hara, 1975; 119 Kasumyan, 2004). This factor can give rise to interspecific differences in the relative importance of 120 vision and other senses (e.g., olfaction and lateral line sense) in solving the detour task. To address 121

- this issue, we compared zebrafish and a control species, the guppy, in a detour task modified to
- assess the role of lateral line information and olfactory cues in solving the task.

124 METHODS

125 Experiment 1: Interspecific differences in detour task performance

126 *Subjects*

Four species of teleost fish (Danio rerio, Oryzias sarasinorum, Poecilia reticulata, Xenotoca eiseni) 127 were tested in this study. Two previous studies have reported sex differences in detour performance 128 in guppies (Lucon-Xiccato & Bisazza, 2017a; Lucon-Xiccato, Gatto & Bisazza, 2019). Therefore, 129 130 we used only adult females to avoid the confound of sex differences. We tested 16 guppies, 16 zebrafish, 16 red-tailed splitfin fish and 16 Sarasins minnows. Guppies are the descendant of wild 131 caught ancestors collected in the lower Tacarigua River (Trinidad) in 2002. They are maintained in 132 133 a large (> 10000 individuals) self-sustaining population in an artificial pond. Twice a year guppies from the pond are collected and used as breeders for the laboratory population. Zebrafish originate 134 from some stocks bought in pet shops in the nineties and maintained since then in the Zebrafish 135 136 facility of University of Padova as a large stock (> 500 fish) and regularly outbred to avoid inbreeding. Zebrafish used in our experiments originated from many different spawnings. They 137 were raised in petri dish for the larval period and then moved to large tanks and raised in the same 138 conditions of the other fish. Red-tailed splitfin fish were bought from a local pet shop in 1996 and 139 140 thereafter maintained in our laboratory in a large population (>300 fish). Sarasins minnows were 141 caught at Lake Poso (Sulawesi, Indonesia) in 1996 and thereafter maintained in our laboratory in a large population (>300 fish). In our laboratory, each species was maintained in large social groups 142 in opaque plastic tanks (400 L or 70 L) with abundant plants and gravel bottoms. A 30-w 143 fluorescent lamp illuminated each tank according to a 12 h:12 h light/dark photoperiod. The water 144 was constantly filtered and maintained at 26 ± 1 °C. Fish were fed twice a day, alternating between 145 146 commercial food flakes (Aqua tropical, Padovan®) and live Artemia salina nauplii. In a recent study, we showed that experience with transparent surfaces does not alter fish performance in the 147 detour task (Santacà et al., 2019). However, at the start of the present study, those results were not 148

available. Therefore, for all four species, we used subjects that had no experience of transparentsurfaces to avoid potential confounding effect of this factor.

Five days before the start of the experiment, subjects were moved in an 80 L habituation tank provided with vegetation, gravel, and filter as described for the previous maintenance tanks. All tanks were covered with thick grey net so that fish could not see through. Inside, we constructed a grey plastic apparatus in the shape of an hourglass (Figure 1a), which was similar to the shape of the experimental apparatus. In this way, subjects could habituate to swimming from one side to the other of the tank passing through a central corridor as in the detour task (see below). One 15-w fluorescent lamp was placed above each half of the tank.

158

159 *Apparatus*

The experimental apparatus (Figure 1b) consisted of three juxtaposed tanks: a central subject tank 160 161 and two lateral stimuli tanks. In the middle of the subject tank ($110 \times 42 \times 35$ cm), a runway (11×9 cm) allowed the fish, at both ends of the runway, to face a C-shaped barrier behind which a social 162 reward was located. The barrier was 15 x 10 cm in size and made of transparent plastic material. 163 Each barrier was displaced 25 cm from the runway that presented two semi-transparent guillotine 164 doors. Two lateral white plastic panels were attached to the barrier to prevent fish from accidentally 165 166 detouring by simply sliding along the barrier. Each short wall of the subject tank was adjacent to a stimuli tank ($60 \times 40 \times 30$ cm) in which eight adult conspecific females were housed. The stimuli 167 tanks were provided with natural gravel bottom, vegetation, filters and two 18-w fluorescent lamps. 168 Inside these tanks, we built a green trapezoidal compartment $(15 \times 10 \times 14 \text{ cm})$ adjacent to the short 169 wall of the subject tank. The background of the compartments was white to improve the visibility of 170 the stimuli. A green plastic sliding panel that could be inserted between the stimuli tanks and the 171 subject tank was used to regulate the sight of the conspecifics during the different phases of the 172 experiment (see below). The stimuli tanks and the subject tank were in olfactive communication by 173

174 means of a system of pumps. A water pump withdrew water from the stimuli tank and directed it in 175 a transparent tube the end of which was placed inside the subject tank. In the subject tank two water 176 pumps released the water in the two stimuli tanks. A video camera was placed above each subject 177 tank barrier to record the experiment.

178

179 *Procedure*

Thirty minutes before the start of the experiment six stimuli were confined in the front compartment 180 of both stimuli tanks. The stimuli were chosen from tanks different from that of the subjects to 181 avoid effects of familiarity (Griffiths & Magurran, 1999). We were not aware of the kin relationship 182 between subjects and stimulus fish. In adult guppies kinship seems to not affect schooling decisions 183 (Griffiths & Magurran, 1999). In zebrafish, kin recognition seems to occur as a consequence of 184 familiarity during early development and was therefore controlled using fish from different tanks 185 (Gerlach, Hodgins-Davis, Avolio, & Schunter, 2008). For the remaining two species, there is not 186 literature on the effects of kinship. However, since fish of the same brood were kept together in the 187 same tank, and subject and stimuli came from different tanks, kinship was not expected to cause 188 substantial effects in our test. During the experiment, subjects were observed in a series of 12 189 consecutive detour trials in which they had to reach one group of conspecifics. Each experiment 190 began with the transfer of a subject from the habituation tank to the runway of the subject tank. The 191 192 sliding panel prevented the subject from seeing one social reward and the corresponding guillotine door was closed. The social reward visible in the first trial was randomized among subjects; this did 193 not affect fish performance (rm ANOVA, $F_{1,63} = 0.199$, P = 0.657. The subject was let free to reach 194 the visible group of conspecifics. Exiting from the runway, the subject had to detour the transparent 195 barrier to reach the conspecifics. Some studies used a pre-training with an opaque barrier that 196 improves subjects' detour performance (Vlamings, Hare, & Call, 2010) and might allow to 197 distinguish between the spatial abilities necessary to perform the detour behaviour and the 198

inhibitory abilities necessary to handle the transparent barrier. We did not perform such pre-training 199 200 because fish reached a similar performance with both procedures (Lucon-Xiccato et al., 2017) and 201 because the aim of our study was not to exclusively investigate inhibitory control. Three minutes after the subject completed the task (i.e., it reached the conspecifics), the sliding panel between the 202 subject tank and the other stimulus tank was removed and the corresponding guillotine door was 203 opened. For the next two minutes, the subject was free to decide to move to the other side of the 204 205 tank in which the other conspecifics were visible. After that time, the sliding panel was placed between the subject tank and the stimulus tank nearer to the subject; the subject was therefore 206 motivated to move to the other test sector. Once the subject passed through the corridor, the more 207 208 distant guillotine door was closed. The procedure was then repeated until the subject performed 12 trials. To eliminate potential directional chemical cues from the previously tested subject, the new 209 subject was tested after half an hour period during which pumps continued to exchange water 210 211 between the subject tank and the stimuli tanks. In addition half of the water of the apparatus was changed after each trial adding new aged water. Two guppies ceased to participate after 10 trials; 212 their performance was analysed only up to that trial. 213

An experimenter observed all trials from a distant monitor connected to the video camera to control 214 215 the doors and the panels of the apparatus. Based on the video recordings, we scored the accuracy of 216 the subjects: we recorded whether the subject attempted to reach the social stimuli by touching the barrier (incorrect trial) or detouring around it directly (correct trial). This measure of accuracy is 217 often used with the detour paradigm but in some cases might poorly describe subjects' performance 218 219 because it is a binomial variable with only two possible outcomes. For example, subjects that persistently try to reach the goal and touch multiple times the barrier would have a score (incorrect 220 trial) that is equal to that of subjects that touch the barrier only once and then immediately correct 221 their behaviour. Therefore, we analysed a second measure of performance that was not binomial. 222 Because fish in the barrier tend to swim with the snout touching the transparency, it was not 223

possible to measure the number of attempts to reach the goal as in some recent studies (van Horik et
al., 2018). Following other studies on the detour behaviour (Kabadayi et al., 2017), we measured
the time that subjects spent trying to pass through the barrier. In all the species, we started to record
this time variable when the subject entered the area delimited by the wings of the barrier with its
snout. One third of the videos of each species were analysed by two different experimenters to
assess inter-rater reliability.

230

231 *Statistical Analysis*

Analyses were performed in R version 3.5.3 (The R Foundation for Statistical Computing, Vienna, 232 233 Austria, http://www.r-project.org). Initially, we assessed inter-rater reliability between the scores of the two experimenters: for the accuracy, we calculated the mean agreement dividing the concordant 234 trials by the total number of trials; for the barrier time, we tested for a correlation between the two 235 236 scorers using Spearman's rank method. As inter-rater reliability was excellent, we conducted the following analyses using the database of the first experimenter. We analysed the subjects' accuracy 237 in each trial (correct or incorrect) with generalized linear mixed-effects models for binomial 238 response distributions (GLMMs, 'glmer' function of the 'lme4' R package). To assess whether 239 240 accuracy increased trial after trial and whether the species differed, we fitted the models with the 241 trial number and the species as fixed effects. In addition, individual ID was fitted as random effect. We also analysed the time (after log transformation due to right-skewed distribution) spent trying to 242 pass though the barrier using linear mixed-effects models (LMMs, 'lmer' function of the 'lme4' R 243 package) fitted with the trial and the species as fixed effects and individual ID as random effect. 244 Subsequently, all pairwise comparisons were performed with Tukey post-hoc tests. Intraspecific 245 differences in performance were investigated by estimating repeatability from GLMM fitted by 246 restricted maximum likelihood (Nakagawa & Schielzeth, 2010). 247

248

249 Experiment 2: Does sociality explain detour task performance?

250 *Subjects, apparatus and procedure*

We tested the same four species of teleost fish (Poecilia reticulata, Danio rerio, Xenotoca eiseni, 251 Oryzias sarasinorum) as in the first experiment. All subjects were adult females and we tested 36 252 guppies, 36 zebrafish, 36 red-tailed splitfin fish and 36 Sarasins minnows overall. All subjects were 253 experimentally naïve and none of them was used in the other two experiments. Fish were tested in 254 255 groups of 3. The experiment was run in a square tank $(70 \times 70 \times 37 \text{ cm})$ filled with 15 cm of water. Its base was covered by a green plastic panel in which twenty-five identical squares were drawn (14 256 \times 14 cm). The lateral sides of the tank were covered by white plastic panels. The tank was 257 258 illuminated by four 18-w fluorescent lamps at a distance of 25 cm from the water's surface and it was placed in a dark room. Three fish were inserted into a transparent cylinder (height: 15 cm; 259 diameter: 12 cm) placed in the central square of the tank. After five minutes, we lifted the cylinder 260 261 and began recording with a digital video camera fixed on the ceiling. Fish were recorded for thirty minutes, after which they were removed from the experimental tank, moved to apposite tanks and 262 kept only for reproduction. Based on the video recordings, we scored two measures of sociality: the 263 inter-individual distance and the number of squares occupied by each school. Videos were digitized 264 using a computer at 12 frames per minute (for a total of 360 images for each group). To calculate 265 266 the inter-individual distance, we used a computer program (written in Delphi5 Borland) that 267 calculated for each school the average distance (snout to snout) between each pair of fish. To calculate the inter-rater reliability of the two measures of sociality, one third of the videos were 268 269 reanalysed by another experimenter.

270

271 *Statistical Analysis*

A Spearman's rank correlation was used to assess inter-rater reliability between the two

273 experimenters who scored the videos. A Pearson correlation test was used to assess the correlation

between the two measures of sociality, the inter-individual distance and the number of squares
occupied by the school. Then, we analysed the mean inter-individual distance (after log
transformation) and the mean number of squares occupied with multivariate analysis of variance
(MANOVA) fitted with the species as fixed effect. Subsequently, all pairwise comparisons were
performed with Tukey post-hoc tests.

279

280 Experiment 3: Sensory information used in detour task

281 *Subjects, apparatus and procedure*

In Experiment 3, we investigated the role of sensory information in the higher performance of 282 283 zebrafish observed in Experiment 1. We tested the zebrafish, which performance deviated from that of the other three species. Because guppies, red-tailed splitfin fish and sarasins minnows showed a 284 similar performance in Experiment 1, in application of the Reduction principle (Russell, Burch, & 285 286 Hume, 1959; Sneddon, Halsey, & Bury, 2017) we decided to test only one of these species as a reference to be compared with the zebrafish. Testing two more species was not expected to provide 287 further information on why zebrafish showed higher detour performance. We used the guppy as 288 reference species because this species is the most studied with this type of task (Gatto et al., 2018; 289 290 Lucon-Xiccato et al., 2017; Lucon-Xiccato & Bertolucci, 2019; Santacà et al., 2019). We tested 291 other 36 guppies and 36 zebrafish in the same apparatus and with the same procedure as in Experiment 1. All 72 fish were experimentally naïve females. In particular, we tested 12 subjects 292 per species in an exact replication of Experiment 1 (Control condition). In a second condition 293 294 (Odour condition), 12 other subjects per species had to detour the same barrier of the Experiment 1 but the odour from the stimuli tank was released before the barrier by moving the end of the 295 transparent tube of the water pumps' system in front of the barrier itself. In a third condition (Net 296 barrier condition), 12 guppies and 12 zebrafish were tested using the same procedure of Experiment 297

1 but the transparent surface of the barrier was substituted with transparent net (mesh size: 0.35 cm;
wire thickness: 0.01 cm). As in Experiment 1, we scored accuracy and barrier time.

300

301 Statistical Analysis

Analyses were similar to those conducted for Experiment 1. To analyse the subjects' accuracy, we 302 fitted a GLMM with the condition (Control condition, Odour condition, Net barrier condition) and 303 the species as fixed effects and individual ID as random effect. We also analysed the time in front 304 of the barrier (after log transformation) using a LMMs fitted with the condition and the species as 305 fixed effects and individual ID as random effect. We did not include the trial as a fixed effect in 306 307 these analyses since, as emerged in the results of Experiment 1, it has no or little effect. In case of significant interaction between fixed effects, we performed similar analyses of the three 308 experimental conditions separately. 309

310 **RESULTS**

311 Experiment 1: Interspecific differences in detour task performance

312 The analysis of fish detour behaviour was highly reliable between the two experimenter: the mean

agreement on accuracy excellent (99%) and the barrier was highly correlated (Spearman's rank

314 correlation: $\rho = 0.975, P < 0.001$).

- The overall time required to complete the 12 trials was 111.35 ± 37.45 min (mean \pm SD) for the 16
- guppies, 96.75 ± 29.13 min for the 16 red-tailed splitfin fish, 89.16 ± 19.92 min for the 16 Sarasins

minnows and 62.96 ± 14.70 min for the 16 zebrafish. The four species showed a significant

difference in accuracy ($\chi^2_3 = 23.250$, P < 0.05; Figure 2a). A Tukey post-hoc test revealed that

- zebrafish accuracy (77.08 \pm 19.36% correct trials, mean \pm SD) was significantly higher than the
- accuracy of the other three species (guppies: $49.90 \pm 18.18\%$; red-tailed splitfin fish: $50.52 \pm$

321 16.24%; Sarasins minnows: $59.90 \pm 15.28\%$; *P* values < 0.02); the accuracy of guppies, red-tailed

splitfin fish and Sarasins minnows did not significantly differ (all P values > 0.3). The accuracy of

the subjects did not significantly vary with the trial ($\chi^2_{11} = 17.483$, P = 0.094) and the interaction

trial x species was not significant ($\chi^2_{33} = 26.289, P = 0.790$).

325 The four species significantly differed in the time spent in front of the barrier (LMM: $F_{3,59} =$

326 28.339, P < 0.001; Figure 2b). A Tukey post-hoc test revealed the same pattern described for the

327 accuracy: zebrafish reached the conspecifics more rapidly than the other three species (guppies:

328 128.16 ± 56.43 s; red-tailed splitfin fish: 76.07 ± 29.35 s; Sarasins minnows: 74.16 ± 59.94 s;

zebrafish: 3.49 ± 2.64 s; all *P* values < 0.0001) while guppies, red-tailed splitfin fish and Sarasins

- minnows did not differ (all P values > 0.2). The time spent in front of the barrier significantly
- decreased over trials (LMM: $F_{11,655} = 3.606$, P < 0.001) and the trial x species interaction was not
- 332 significant (LMM: $F_{33,655} = 1.069, P = 0.366$).
- 333 Data of individual subjects are showed in Figure 2c. Intraspecific analysis revealed low but
- significant repeatability in subjects' accuracy across trials in zebrafish (R = 0.11, CI = [0, 0.26], P =

335 0.002). Graphical inspection of individual accuracy indicated that this effect could be due to two 336 zebrafish that showed substantially low performance (Figure 2c). Removing these two subjects 337 from the analysis resulted in non-significant repeatability of zebrafish' accuracy (R < 0.01, CI = [0, 0.07], P = 1). None of the remaining species showed significant repeatability of individual 339 performance (guppies: R = 0.04, CI = [0, 0.13], P = 0.122; red-tailed splitfin fish: R = 0.02, CI = [0, 0.09], P = 0.306; Sarasins minnows: R = 0.01, CI = [0, 0.07], P = 0.385; Figure 2c).

341

342 Experiment 2: Does sociality explain detour task performance?

343 The inter-rater reliability was high for both measures of sociality were high (inter-individual

distance, Spearman's rank correlation: $\rho = 0.971$, P < 0.001; mean number of squares occupied: $\rho = 0.995$, P < 0.001).

The two measures of sociality, inter-individual distance and number of squares occupied by the 346 347 school, were positively correlated (Pearson correlation r(58) = 0.785, P < 0.001). The MANOVA revealed a significant effect of the species ($F_{6,112} = 20.427$, P < 0.001). A Tukey post-hoc test 348 revealed a significant difference between Sarasins minnows and guppies (P < 0.01; Figure 3a) 349 regarding the inter-individual distance; all other comparisons were nonsignificant (all P values > 350 0.5; Figure 3a). Regarding the number of squares occupied, a Tukey post-hoc test revealed that 351 352 Sarasins minnows significantly differed compared to the other three species (all P values < 0.05; Figure 3b). Guppies, zebrafish and red-tailed splitfin fish did not differ (all P values > 0.4; Figure 353 3b). 354

355

356 Experiment 3: Sensory information used in detour task

The trial-by-trial inter-rater reliability on the accuracy was excellent (99%). Even regarding the barrier time, we found a high inter-observer reliability (Spearman's rank correlation: $\rho = 0.989$, P < 0.001).

The GLMM conducted on the accuracy revealed no significant effect of the condition ($\chi^2_2 = 4.633$, 360 P = 0.099) but revealed a significant effect of the species ($\chi^2_1 = 5.712$, P < 0.05). The interaction 361 condition x species was significant ($\chi^2_2 = 19.814$, P < 0.001), indicating that guppies and zebrafish 362 performed differently depending upon the condition. Considering only the Control condition, the 363 GLMM revealed a significant difference between the accuracy of the 12 guppies and the 12 364 zebrafish ($\chi^2_1 = 23.417$, P < 0.001; Figure 4a) confirming the results of Experiment 1. Considering 365 the Odour condition, the accuracy of the two species did not significantly differ ($\chi^2_1 = 1.229$, P =366 0.268; Figure 4a). Also comparing the 12 guppies and the 12 zebrafish considering the Net barrier 367 condition, we found no significant difference between their accuracy ($\chi^{2}_{1} = 0.690$, P = 0.406; Figure 368 4a). 369

370 Regarding the barrier time, we found a similar scenario: the LMM revealed no significant effect of

the condition ($F_{2,66} = 2.917$, P = 0.061) but revealed a significant effect of the species ($F_{1,66} =$

372 10.100, P < 0.001). The interaction condition x species was significant ($F_{2,66} = 4.199, P < 0.05$). In

the Control condition, guppies and zebrafish significantly differed (LMM: $F_{1,22} = 52.577$, $P < 10^{-10}$

374 0.001; Figure 4b). The two species did not differ in the Odour condition (LMM: $F_{1,22} = 0.594$, P =

375 0.449; Figure 4b). A significant difference between guppies and zebrafish emerged in the Net

376 barrier condition (LMM: $F_{1,22} = 9.872$, P < 0.01; Figure 4b).

377 DISCUSSION

378 In Experiment 1, three out of four tested species (guppies, red-tailed splitfin fish and Sarasins

379 minnows) showed a performance similar to that exhibited by guppies in the previous study (approx.

380 50% correct response; Lucon-Xiccato et al., 2017) and comparable to the average score of birds and

mammals, excluding monkeys and great apes (MacLean et al., 2014). The fourth species, zebrafish,

scored much higher in accuracy and spent less time on the barrier. In particular, the percentage of

correct trials of zebrafish (77%) matches that of various species of corvids and monkeys (e.g.,

Papio anubis: 76%; *Macaca mulatta*: 80%; *Aphelocoma californica*: 77%; MacLean et al., 2014). It

is interesting to note that 75% of zebrafish performed correctly on the first trial while in the other
three fish species this proportion ranges between 25% and 50%.

387 In contrast to the difference between species, the individual subjects performed quite similarly within-species. This result seems to contrapose to the growing evidence of individual differences in 388 389 cognition in fish (Lucon-Xiccato & Bisazza, 2017b) and to the fact that other species exhibit individual differences in detour tasks (Baragli, Vitale, Sighieri, Lanata, Palagi, & Reddon, 2017; 390 Shaw, 2017). On the other hand, the low intraspecific variability in performance further increases 391 our confidence in the results of the comparison between species. For example, 8 out 11 subjects that 392 performed > 75% correct responses were zebrafish. Therefore, the higher performance of zebrafish 393 394 was unlikely explained by individual differences and random fluctuations in the performance of few individuals. 395

There could be various explanations for the higher performance of zebrafish in Experiment 1. One is that the four species, because of their different ecology, differ in term of one or more of the cognitive skills that are involved to detour task solution. In particular, the differential presence of obstacles, which could block a direct path to a goal, in the natural habitat of a species is expected to cause diverse intensity of selection on its detour ability. However, this scenario does not appear compatible with our results. The presence of obstacles in the natural habitat of Sarasins minnows

was likely very scarce in its evolutionary past, because this species is pelagic and endemic of a 402 403 single large tropical lake (Kottelat, 1990; Parenti, 2008). Conversely, the other three species live in 404 tropical rivers, often containing vegetation (although this factor may be scarce in some habitats of the red-tailed splitfin fish), rocks, rapids and other obstacles (Magurran, 2005; Piller et al., 2015; 405 Roy & Bhat, 2018); these three latter species were expected to undergo convergent evolution for 406 high detour capacities. Other things being equal, we expect Sarasins minnows to exhibit the lower 407 408 detour performance, which did not occur in our experiment. One could hypothesise that other aspects of species ecology, such as the schooling behaviour, affect detour performance. However, to 409 the best of our knowledge, the current literature does not provide indications with this respect. 410 411 Excluding alternative ecological explanations would require more data on the natural behaviour of 412 the species used in this study and data on the detour performance of many more species. Other evidence is against the hypothesis that the observed differences in detour test performance 413 414 were due to interspecific variation in cognitive skills. One could suggest, for example, that the four species differ in learning the properties of the transparent barrier (i.e., its impenetrability). Learning 415 however, does not appear substantially involved in our task because we did not observe a significant 416 improvement in accuracy over trials. Zebrafish could have more efficient spatial abilities, problem 417 solving, or in inhibitory motor control skills than the other three species. The limited data in this 418 419 regard seem to suggest that cognitive abilities of zebrafish are at best similar to those of the other three species examined. In a recent study, zebrafish performance did not differ from that of other 420 fish species (including red-tailed splitfin fish) in a route planning task (Sovrano, Baratti, & Potrich, 421 422 2018). In a numerical abilities' study, zebrafish showed lower learning performance compared to guppy and red-tailed splitfin (Agrillo, Miletto Petrazzini, Tagliapietra, & Bisazza, 2012). In 423 addition, recent studies tested zebrafish and guppies in a task designed to measure inhibition in 424 which a food reward is placed inside a transparent tube and the subjects had to inhibit the tendency 425

to bite it; results indicate that zebrafish and guppies have similar capacity to learn to inhibit a 426 427 response (Lucon-Xiccato, Bisazza, & Bertolucci, 2019; Lucon-Xiccato & Bertolucci, 2019). Alternatively, the differences observed in Experiment 1 could be due to non-cognitive factors. 428 Despite our attempt to maintain similar pre-test conditions (e.g., all the subjects experienced the 429 same rearing conditions, and they had no previous experience with transparent surfaces and with 430 detour tasks), other factors could have differentially affected the performance for the four species. 431 432 For example, all four species are social to some degree, but the importance of living in a group could differ among them. In turn, a stronger attraction to social companions could have potentially 433 made it more difficult to inhibit the response of swimming through the barrier as observed with 434 435 food lures in other species (Brucks, Soliani, Range, & Marshall-Pescini, 2017; Auersperg, Laumer, & Bugnyar, 2013). In Experiment 2 we measured the tendency of the four species to aggregate 436 when placed in a novel environment. We found a certain heterogeneity in their gregarious 437 438 tendencies, but a different degree of sociality does not seem to explain the results of Experiment 1 as zebrafish was not found to be more gregarious than the other species. 439 The results of Experiment 1 could also be explained by sensorial differences among the species 440 studied. Ostariophysi (the clade to which zebrafish belongs) and Acanthopterygii (to which the 441 442 other three species belong) evolved separately for approximately 220 million years ago (Steinke, 443 Salzburger, & Meyer, 2006). Beloniformes (the order to which the Sarasins minnow belongs) diverged from Cyprinodontiformes (to which guppies and red-tailed splitfin fish belong) 444 approximately 150 million years ago, while the phylogenetic distance between guppies and red-445 tailed splitfin fish is smaller, approximately 65 million years (Meyer & Lydeard, 1993; Pohl, 446 Milvertz, Meyer, & Vences, 2015; Reznick, Furness, Meredith, & Springer, 2017). Therefore, wide 447 448 differences in sensory systems could have reasonably evolved. For a fish species that relies more on vision to navigate and find conspecifics, the transparent barrier could be almost imperceptible. On 449 the contrary, if a species uses other sensory modalities, for example, lateral line sense or olfaction, a 450

solid obstacle is perceived in the same way regardless of whether it is transparent or opaque. To test 451 452 this possibility, in one of the conditions of Experiment 3 we compared zebrafish and guppies after replacing the barrier of transparent plastic material with a barrier made with a thin monofilament 453 net. The obstacle was still invisible but here we minimized surface available to generate a pressure 454 gradient typically produced by an approaching object to substantially reduce its detectability by the 455 lateral line system. This experimental manipulation eliminated the performance advantage of 456 457 zebrafish over guppies suggesting a possible implication of the lateral line. However, the net barrier was also transparent to the odours coming from social stimuli, so interspecific differences in the 458 importance of olfaction was also a candidate for explanation. In Experiment 1 in fact, the same 459 460 facilitation effect could have occurred if a fish located conspecifics primarily using olfaction. In our experimental setup, due to the system of water pumps, there was a constant flow of water from the 461 shoal of conspecifics to the starting point in the central corridor. Because the transparent barrier was 462 463 opaque to odour, scent from the stimulus shoal followed the same pathway that the animal had to take to solve the detour task. To unravel this point, in the second condition of Experiment 3 we 464 retained the original transparent barrier but the odour flow was released before the barrier to prevent 465 any directional odour hint from the stimuli. Even in this case the advantage of zebrafish over 466 guppies was nullified, suggesting that zebrafish were taking advantage of odour cues in the classical 467 468 detour condition of Experiment 1. An implication of odour cues could also explain why, in zebrafish, the majority of subjects performed the detour task correctly even on the first trial, as 469 though they could perceive the invisible obstacle. The result of the odour manipulation condition 470 suggests that the olfactory factor could also be responsible for the result of the net barrier condition, 471 although the implication of the lateral line system in avoiding transparent obstacles is not ruled out 472 473 by our study.

As in other taxonomic groups such as mammals, among fish there are microsmatic and macrosmatic
species that prioritise cues from the visual system or the olfactory system, respectively, in relevant

contexts such as social, sexual, navigation, feeding and predatory behaviours (Hara, 1975; 476 477 Kasumyan, 2004). Traditionally, guppies are considered to be a microsmatic species that relies mainly on vision while zebrafish, is typically macrosmatic one (Lazzari, Bettini, & Franceschini, 478 2014). The two distinctive groups present evident differences in the morphology of the olfactory 479 mucosa. For example, macrosmatic fish species have well developed multilamellar olfactory 480 rosettes with a behaviourally predominant olfactory ability. In contrast, microsmatic species possess 481 less developed, even unilamellar olfactory rosettes (Lazzari et al., 2014). It is interesting to note that 482 a recent work demonstrated that olfactory cues do not appear to affect guppy performance in 483 another type of detour task, the cylinder test in which a fish has to enter from the lateral opening of 484 485 a transparent cylinder to obtain food (Santacà et al., 2019). It remains to be assessed whether microsmatic fish species such as zebrafish enjoy a sensorial advantage in this test as well. 486 Overall, our study provides evidence that large interspecific variation in performing the detour task 487 488 may be the consequence of non-cognitive confounding effects, rather than reflecting a difference in one or more cognitive abilities important for carrying out the task. In particular, sensorial 489 differences were responsible for a two-fold difference in accuracy and three-fold difference in the 490 time spent in front of the barrier between macro- and microsmatic species. This has important 491 492 implications for the interpretation of recent attempts to reconstruct the evolution of complex 493 cognitive functions, such as inhibitory control, using detour-like tasks: the amount of variation due to sensory differences found here appears in fact much wider than the average variation observed 494 among species (Kabadayi et al., 2016; Brucks et al., 2017; van Horik et al., 2018). There is a long-495 standing debate in comparative cognition about the risk that observed differences in performance 496 may be due to contextual variables rather than species' differences in cognitive ability (MacPhail, 497 1987; Shettleworth, 2010). Our work further highlights the need to adopt an adequate approach to 498 address this important problem (Bitterman, 1975; Kamil, 1988). 499

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620 Figure captions

621	Figure	1
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- 622 Representation of the habituation tank (A) and representation of the experimental apparatus (B).
- 623 The experimental apparatus was composed of the subject tank (a) and two stimuli tanks (b). The
- 624 subject tank was composed of a central runaway (c), two transparent barriers (d), and two semi-
- transparent guillotine doors (e). A green plastic sliding panel (f) regulated the sight of the
- 626 conspecifics; a system of pumps (g) allowed olfactory cues of the stimulus to permeate the subject

627 tank.

628 **Figure 2**.

629 Results of Experiment 1: mean accuracy (A) and mean barrier time (B) after log transformation

630 divided in the 12 trials, and overall accuracy of the individual subjects (C) for the four species of

631 teleost fish (*Poecilia reticulata*, *Danio rerio*, *Xenotoca eiseni*, *Oryzias sarasinorum*). Bars represent

632 the standard error.

633 **Figure 3**.

Results of Experiment 2: mean inter-individual distance (A) and mean number of squares occupied

by the school (B), for the four species of teleost fish (*Poecilia reticulata*, *Danio rerio*, *Xenotoca*

eiseni, *Oryzias sarasinorum*). Asterisks denote a significant departure from chance level (P < 0.05).

637 Bars represent the standard error.

- 638 **Figure 4**.
- Results of Experiment 3: mean accuracy (A) and mean barrier time (B), after log transformation, for
 the three conditions (Control condition, Odour condition, Net barrier condition) for guppies and
- 641 zebrafish. Asterisks denote a significant departure from chance level (P < 0.05). Bars represent the 642 standard error.
- 643